# Geometric integrators with complex coefficients 

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FoCM'11, Budapest, July 4-14, 2011
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The numerical integration of non-reversible systems using high order splitting methods with complex coefficients (having positive real part) has been recently considered Example: The linear heat equation with potential

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\frac{\partial}{\partial t} \mathbf{u}=\triangle \mathbf{u}+V(x) \mathbf{u}
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New families of numerical methods have appeared which deserve further analysis.
Some questions:

- $\exists$ methods at any order with coefficients having positive real parts?
- Are the new methods efficient?
- Are useful for long time integrations? Backward error analysis?


## Introduction

- From the computational point of view:
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- From the theoretical point of view:
- Singularities in the complex domain can appear
- Bounded solutions in the real space are unbounded in the complex domain, and this can affect to the stability of the methods
- The evolution of the solution on the extended manifold in the complex domain needs to be studied


## Example: The Volterra-Lotka problem

Let us consider the Volterra-Lotka problem

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\dot{u}=u(v-2), \quad \dot{v}=v(1-u)
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First integral: $I(u, v)=\ln \left(u v^{2}\right)-(u+v)$.

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It can be considered as a Hamiltonian system with

$$
H=\left(2 p-e^{p}\right)+\left(q-e^{q}\right)
$$

with $q=\ln u, p=\ln v$
Split: $f_{A}=(u(v-2), 0), \quad f_{B}=(0, v(1-u))$

## A simple 4th-order method

Given a symmetric 2nd order $\mathcal{S}^{[2]}$ one gets a 4th order integrator $\mathcal{S}^{[4]}: \mathbb{R}^{2 d} \rightarrow \mathbb{R}^{2 d}$ as

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\begin{gathered}
\mathcal{S}_{h}^{[4]}=\mathcal{S}_{\alpha h}^{[2]} \circ \mathcal{S}_{\beta h}^{[2]} \circ \mathcal{S}_{\alpha h}^{[2]}, \\
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Initial conditions $\left(u_{0}, v_{0}\right)=(4,2), \quad t \in[0,1000]$

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## Example:



## 4th-order Methods by Composition

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If $\alpha_{i} \in \mathbb{C}$ then

$$
\max _{i=1, \ldots, k} \operatorname{Arg}\left(\alpha_{i}\right)-\min _{i=1, \ldots, k} \operatorname{Arg}\left(\alpha_{i}\right) \geq \frac{\pi}{3} .
$$

Given a symmetric method of order $2 p, \mathcal{S}^{[2 p]}(h)$, we can define a recursion by symmetric compositions

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\mathcal{S}^{[2 p+2]}(h)=\prod_{i=1}^{m_{p}} \mathcal{S}^{[2 p]}\left(\alpha_{p, i} h\right)
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Starting from $\mathcal{S}^{[2]}(h)$, we have
$\mathcal{S}^{[2(p+1)]}(h)=\prod_{i_{\rho}=1}^{m_{\rho}}\left(\prod_{i_{\rho-1}=1}^{m_{\rho-1}}\left(\cdots\left(\prod_{i_{1}=1}^{m_{1}} \mathcal{S}^{[2]}\left(\alpha_{\rho, i_{p}} \alpha_{\rho-1, i_{p-1}} \cdots \alpha_{1, i_{1}} h\right)\right) \cdots\right)\right.$

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Castella, Chartier, Descombes, \& Vilmart, BIT 49 (2009), 487-508, and Hansen \& Ostermann, BIT 49 (2009), 527-542, obtained methods up to order 14 with coefs. having positive real part.

$$
\mathcal{S}_{h}^{[2]} \rightarrow \mathcal{S}_{h}^{[4]} \rightarrow \mathcal{S}_{h}^{[6]} \rightarrow \mathcal{S}_{h}^{[8]} \rightarrow \ldots \mathcal{S}_{h}^{[14]} \rightarrow \mathcal{S}_{h}^{[16]}
$$

## Lemma

For $k \geq 2$ and $r \geq 2$, consider $\left(z_{1}, \ldots, z_{k}\right) \in\left(\mathbb{C}_{+}\right)^{k}$ such that $\sum_{i=1}^{k} z_{i}^{r}=0$. Then we have

$$
\max _{i=1, \ldots, k} \operatorname{Arg}\left(z_{i}\right)-\min _{i=1, \ldots, k} \operatorname{Arg}\left(z_{i}\right) \geq \frac{\pi}{r}
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## Proof.

If

$$
\max _{i=1, \ldots, k} \operatorname{Arg}\left(z_{i}\right)-\min _{i=1, \ldots, k} \operatorname{Arg}\left(z_{i}\right)<\frac{\pi}{r}
$$

then

$$
\max _{i=1, \ldots, k} \operatorname{Arg}\left(z_{i}^{r}\right)-\min _{i=1, \ldots, k} \operatorname{Arg}\left(z_{i}^{r}\right)<\pi
$$

and obviously $\sum_{i=1}^{k} z_{i}^{r} \neq 0$.

## Composition Methods with Complex Coefficients

## Theorem

Starting from a second-order symmetric method $\mathcal{S}^{[2]}(h)$, all methods $\mathcal{S}^{[2 p]}(h)$ of order $2 p=16,18, \ldots$ from the previous recursion have at least one coefficient with negative real part.

## Composition Methods with Complex Coefficients

## Proof.

We assume that all methods $\mathcal{S}^{[2 q]}(h), q=1, \ldots, p$ have all their coefficients in $\mathbb{C}_{+}$. Using Lemma 1 we have
$\forall q=1, \ldots, p, \quad \max _{i=1, \ldots, m_{q}} \operatorname{Arg}\left(\alpha_{q, i}\right)-\min _{i=1, \ldots, m_{q}} \operatorname{Arg}\left(\alpha_{q, i}\right) \geq \frac{\pi}{2 q+1}$,
so that
$\max _{i_{1}, \ldots, i_{p}} \operatorname{Arg}\left(\prod_{j=1}^{p} \alpha_{j, i_{j}}\right)-\min _{i_{1}, \ldots, i_{p}} \operatorname{Arg}\left(\prod_{j=1}^{p} \alpha_{j, i_{j}}\right) \geq \frac{\pi}{3}+\cdots+\frac{\pi}{2 p+1}$.
Since $\frac{1}{3}+\frac{1}{5}+\cdots+\frac{1}{15}>1$, then $2 p=14$ is an upper bound.

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Since $\frac{1}{3}+\frac{1}{5}+\cdots+\frac{1}{15}>1$, then $2 p=14$ is an upper bound.
This is a sharp bound since methods of order 14 have been obtained

## Composition Methods with Complex Coefficients

From the computational point of view, it is more efficient to build methods directly by the composition

$$
\mathcal{S}^{[2 p]}(h)=\mathcal{S}^{[2]}\left(\gamma_{1} h\right) \cdots \mathcal{S}^{[2]}\left(\gamma_{s} h\right)
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We have built methods of order 6 and 8 :

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\begin{aligned}
& \mathcal{S}^{[6]}(h)=\mathcal{S}^{[2]}\left(\gamma_{1} h\right) \cdots \mathcal{S}^{[2]}\left(\gamma_{7} h\right) \\
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We have also built methods of order 16 with coefficients having their real part positive. The procedure followed is:

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$\exists$ methods at all orders? We are still ignorant, but at a higher level of ignorance!

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Initial conditions $\left(u_{0}, v_{0}\right)=(4,2)$, time step: $h=\frac{1}{8}$ Measure the relative error: $\left|I-I_{0}\right| /\left|I_{0}\right|$ with $I(u, v)=\ln \left(u v^{2}\right)-(u+v)$.

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- I) Projection at the end of the integration
- II) Projection at each step


## Example:



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Let $\Phi(h)=e^{h F}$ denote the exact solution and $S_{r}(h)$ a with complex coefficients method of order $r=\min \{q, p\}$ such that

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S_{r}(h)=\exp \left(h F+h^{q+1} F_{R}+i h^{p+1} F_{l}\right)
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$F_{R}, F_{I}$ are elements of the Lie algebra associated to the components of $F$, but $\hat{F}_{l}^{2}$ is not in the Lie algebra.

## Projection into the real space. Informal proof

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To project at the end corresponds to $(t=N h)$

$$
\operatorname{Re}\left(S_{p}^{N}(h)\right)=\left(I-t^{2} h^{2 p} \check{F}_{l}^{2}+\ldots\right) \exp \left(t\left(F+h^{q} \check{F}_{R}\right)\right)
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while to project at each step corresponds to

$$
\operatorname{Re}\left(S_{p}(h)\right)^{N}=\left(I-t h^{2 p+1} \check{F}_{l}^{2}+\ldots\right) \exp \left(t\left(F+h^{q} \check{F}_{R}\right)\right)
$$

## Some other problems of interest

(a) The linear Schrödinger equation $(\hbar=1)$ :

$$
\begin{aligned}
& i \frac{\partial}{\partial t} \Psi(x, t)=\left(-\frac{1}{2 m} \nabla^{2}+V(x)\right) \Psi(x, t) \\
& \mathbf{u}(h)=e^{i h(\Delta+\mathbf{V})} \mathbf{u}_{0}
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Methods with $\quad a_{i} \in \mathbb{R}^{+}, b_{i} \in \mathbb{C}$.

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Methods with $\quad a_{i} \in \mathbb{R}^{+}, b_{i} \in \mathbb{C}$.
(b) The LSE integrated in the pure imaginary time

$$
\frac{\partial}{\partial \tau} \Psi(x, \tau)=\left(\frac{1}{2 m} \nabla^{2}-V(x)\right) \Psi(x, \tau)
$$

Methods with $a_{i}, b_{i} \in \mathbb{C}_{+}$.
In addition

$$
\left[V,\left[V,\left[V, \nabla^{2}\right]\right]\right]=0
$$

## References

R．I．McLachlan and R．Quispel，Splitting methods，Acta Numerica 11 （2002），pp．341－434．

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## Numerical Examples: A linear parabolic equation

Let us consider the scalar equation in one-dimension

$$
\frac{\partial u}{\partial t}=\Delta u+(2+\sin (2 \pi x)) u
$$

$u(x, 0)=\sin (2 \pi x)$
$x \in[0,1]$ with $N=100$
periodic boundary conditions.

## Example:



## Example:



