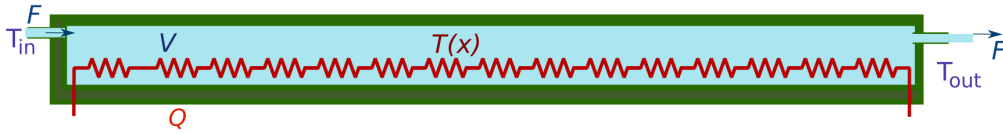


# Tubular heater: simulation of PDE solution

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Video-presentation: <http://personales.upv.es/asala/YT/V/termedpstepEN.html>

**Objectives:** Understand the PDE solution (step response).



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## Modelling

### Partial differential equation

This is the EDP, discussed in other materials:

$$\frac{\partial T}{\partial t} = -\frac{1}{S} F \frac{\partial T}{\partial x} - \frac{\bar{\kappa}}{S\rho C_e} T + \frac{\bar{Q}}{S\rho C_e}$$

Particular cases of interest are:

- With  $\bar{Q} = 0$  and  $\bar{\kappa} = 0$  we get the 1D transport delay equation  $\frac{\partial T}{\partial t} = -v \frac{\partial T}{\partial x}$ , being  $v = \frac{F}{S}$  the linear transport speed.
- Steady state,  $\frac{\partial T}{\partial t} = 0$ ; denoting the solution as  $T_{eq}(x)$ , we have  $\frac{\partial T_{eq}}{\partial x} = -\frac{\bar{\kappa}}{F\rho C_e} T_{eq} + \frac{1}{F\rho C_e} \bar{Q}_{eq}(x)$ .

With constant heating power along all the pipe length, defining  $\lambda = \frac{\bar{\kappa}}{F\rho C_e}$ , we get:

$$T_{eq}(x) = T_{in} \cdot e^{-\lambda \cdot x} + (1 - e^{-\lambda \cdot x})\bar{\kappa}^{-1} \cdot \bar{Q}_{eq}$$

### Transfer function representation for constant flow (zero initial conditions)

We will work with the EDP

$$\frac{\partial T}{\partial t} = -v \frac{\partial T}{\partial x} - aT + b\bar{Q}$$

where  $a = \frac{\bar{\kappa}}{S\rho C_e}$ ,  $b = \frac{1}{S\rho C_e}$ ,  $v = \frac{F}{S}$ , to streamline notation. For constant flow, uniform heating power, solving the EDP via Laplace method, we get the transfer function (for each  $x$ ):

$$\mathbb{T}(x, s) = (1 - e^{-\frac{s+a}{v} \cdot x}) \frac{b}{(s+a)} \cdot \bar{Q}(s) + \mathbb{T}_{in}(s) e^{-\frac{s+a}{v} \cdot x}$$

**Steady state:** if  $\bar{Q}$  and  $T_{in}$  were constant, we would obtain steady-state equations replacing  $s$  by zero:

$$T_{eq}(x) = (1 - e^{-\frac{a}{v} \cdot x}) \frac{b}{a} \cdot \bar{Q}_{eq} + T_{in,eq} e^{-\frac{a}{v} \cdot x}, \text{ obviously coincident with the formula above for this case.}$$

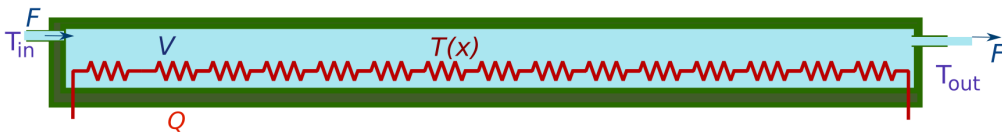
**Outlet temperature transient (Laplace domain):**

Denoting  $\phi = L/v$ , we have:

$$\mathbb{T}_{out}(s) = \left( (1 - e^{-\phi \cdot s} e^{-a\phi}) \frac{b}{s+a} \quad e^{-\phi \cdot s} e^{-a\phi} \right) \cdot \begin{pmatrix} \bar{Q}(s) \\ \mathbb{T}_{in}(s) \end{pmatrix}$$

where the coefficients as a function of physical parameters are  $a = \frac{\bar{\kappa}}{S\rho C_e}$ ,  $b = \frac{1}{S\rho C_e}$ ,  $v = \frac{F}{S}$ ,

$$\phi = \frac{L}{v} = \frac{V}{F}, \text{ and, hence, } a\phi = \frac{\bar{\kappa}L}{F\rho C_e} = \frac{\bar{\kappa}L}{vS\rho C_e}$$



**Exact simulation of the EDP solution (only outlet temp.)**

**Simulación exacta (control systems toolbox)**

We'll set some values for physical parameters

```
S=0.0008;rho=1000;Ce=4180;barkappa=1.5e-1;
Ltot=2; %Total length (later on, we'll divide in several "finite elements" of 1st order
F=0.00015; %cubic meters per second
```

So the coefficients of the transfer functions are:

```
b=1/S/rho/Ce*1e3 %we assume input in Kw per meter
```

```
b = 0.2990
```

```
a=b*barkappa
```

```
a = 0.0449
```

```
L=Ltot; %a single element with all of the heater's length  
V=S*L %cubic meters
```

```
v = 0.0016
```

```
v=F/S %linear speed
```

```
v = 0.1875
```

```
phi=L/v%flushing time.
```

```
phi = 10.6667
```

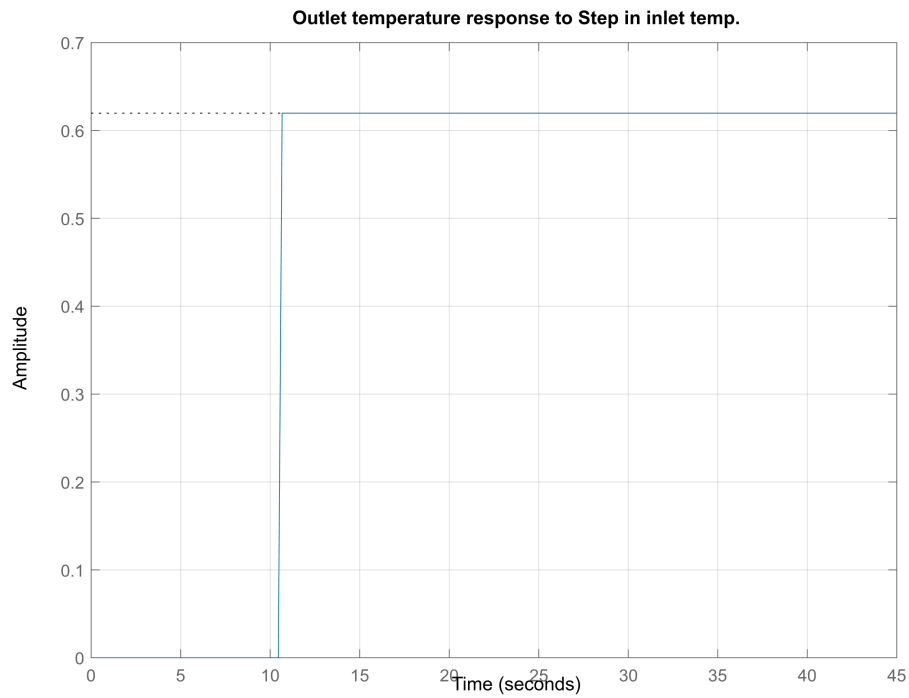
```
expphia=exp(-phi*a) %longitudinal temperature decay from PDE solution
```

```
expphia = 0.6197
```

### Inlet Temperature step

It is just a static gain plus delay:

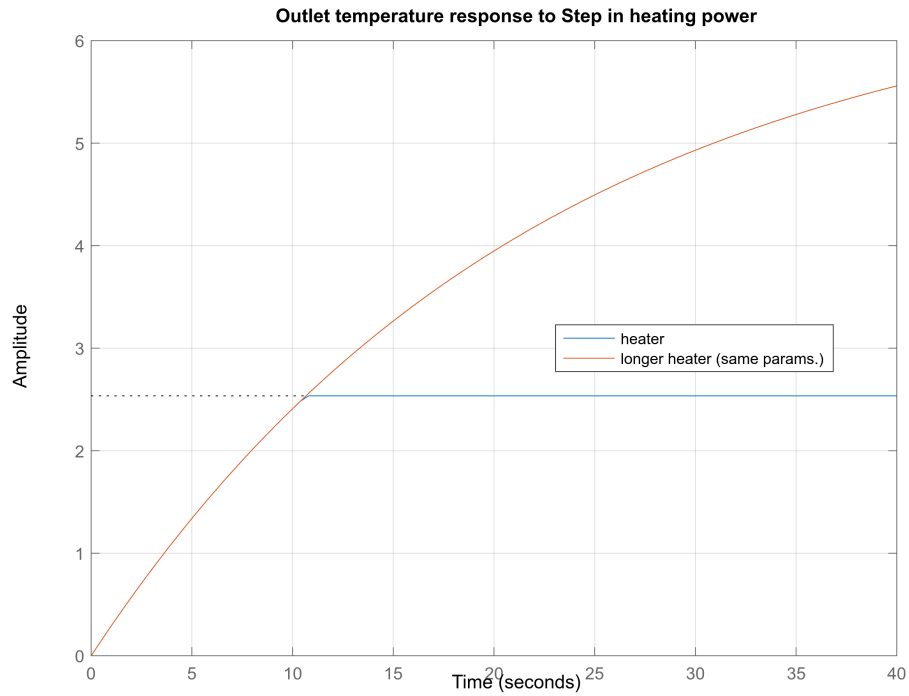
```
s=tf('s');  
sysTin=exp(-a*phi)*exp(-phi*s);  
sysQ=(1-sysTin)*b/(s+a);  
sysPDE=[sysQ sysTin];  
step(sysTin), grid on, title("Outlet temperature response to Step in inlet temp.")
```



### Heating power step

It's a usual 1st-order step response but "truncated" when pipe ends and the fluid stops heating:

```
step(sysQ,b/(s+a),40), grid on, title("Outlet temperature response to Step in heating power",Location="top")
legend("heater", "longer heater (same params.)",Location="best")
```



We can simulate two particular cases:

- lossless (  $a = 0$  ): the outlet temperature is exactly  $T_{in}$  delayed by flushing time; a step in  $Q$  produces the step response of  $\frac{1 - e^{-\phi s}}{s} b$  which is a ramp ascending during the flushing time with slope  $b$  and later on keeping the constant value  $\phi b$ .
- With losses (  $a > 0$  ), what we presented above: delay plus gain in response to inle temperature and truncated 1st order response to step in  $Q$ , the response of  $\frac{b}{s + a}$ , truncated at  $t = \phi$  constant from that instant at the value  $\frac{b}{a}(1 - e^{-a\phi})$ .