



$$J \frac{d^2 \alpha}{dt^2} = Mg \cdot L \sin \alpha + T_{manip}$$

$$\alpha \approx 0 \quad \downarrow \quad s^2 \alpha(s) - s\alpha(0) - \alpha'(0)$$

$$J \frac{d^2 \alpha}{dt^2} = Mg \cdot L \cdot \alpha + T_{manip}$$

$$(Js^2 - MgL) \cdot \alpha(s) = T_{manip}(s) + J \cdot (s\alpha(0) + \alpha'(0))$$

$$\alpha(s) = \frac{1}{Js^2 - MgL} \cdot (T_{manip}(s) + J \cdot (s\alpha(0) + \alpha'(0)))$$

$$\alpha(s) = \frac{1/J}{s^2 - MgL/J} \cdot T_{manip}(s) + \frac{s\alpha(0) + \alpha'(0)}{s^2 - MgL/J} \quad p = \sqrt{\frac{MgL}{J}}$$

$$\alpha(s) = \underbrace{\frac{1/J}{(s+p)(s-p)}}_{TF} T_{manip}(s) + \underbrace{\frac{s\alpha(0) + \alpha'(0)}{(s+p)(s-p)}}_{i.c. term}$$

$$\alpha(s) = \frac{2}{(s+1)(s-1)} \cdot T_{manip}(s)$$

Free req: ( $T_{manip} = 0$ )

$$(\alpha(0), \alpha'(0) = 0)$$

$$\alpha(s) = \frac{\alpha(0) \cdot s}{(s+1)(s-1)} = \frac{0.5\alpha(0)}{s+1} + \frac{0.5\alpha(0)}{s-1}$$

$$0.5\alpha(0) (e^{-pt} + e^{+pt})$$

$\infty$

